



Maximum Product Spacings for the Kumaraswamy Distributions Based on Progressive Type-II Censoring Schemes

prepared by

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Abstract

The Type-II progressive censoring schemes of maximum product spacing will be discussed. In this paper, we have studied the problem of point estimation of the two parameters for the Kumaraswamy distribution based on progressive Type-II censoring. The maximum product spacing is used to estimate the model's parameters. To evaluate the performance of the point estimator, the simulation study is carried out. To illustrate the usefulness of the study in practice, a real data is used to study the performance of the estimation process under this progressive Type-II censoring scheme. In this paper, we have considered the problem of estimation of the unknown parameters for Kumaraswamy distribution under progressive Type-II censoring. We derived maximum product spacings estimates for the unknown parameters of a Kumaraswamy distribution. To illustrate the usefulness of the study in practice, a real data is used to study the performance of the estimation process under this progressive Type-II censoring scheme. In this paper, although we have mainly considered Type-II progressive censoring cases, the same method can be extended to other censoring schemes also.

Keywords

Kumaraswamy distribution, progressive Type-II censoring, Maximum product spacing estimation.

1. Introduction

The Kumaraswamy distribution is similar to the Beta distribution, but it has a notable advantage of having an invertible cumulative distribution function that can be expressed in a closed-form. Kumaraswamy (1976, 1978) showed that commonly used probability distribution functions like the normal, lognormal, and beta distributions do not adequately model hydrological data such as daily rainfall and stream flow. As a result, Kum. introduced a new probability density function known as the sine power probability density function.

Kumaraswamy (1980) introduced the Kumaraswamy distribution as a versatile probability density function for double-bounded random processes. This distribution is suitable for modeling various natural phenomena with lower and upper bounds, such as individual heights, test scores, atmospheric temperatures, hydrological data, and more. Additionally, the Kumaraswamy distribution can be used when scientists need to model data with finite bounds, even if they are using probability distributions with infinite bounds in their analysis. The Kumaraswamy distribution's probability density function (pdf) is described by

$$f(x) = \alpha \beta x^{\alpha - 1} (1 - x^{\alpha})^{\beta - 1}$$
(1)

where 0 < x < 1 and α, β are two positive shape parameters. When $\alpha = 1$ and $\beta = 1$, then one can obtain a Uniform distribution U(0, 1) as special case of the Kumaraswamy distribution. The cumulative distribution function (cdf) of the Kumaraswamy distribution is given by

$$F(x) = 1 - (1 - x^{\alpha})^{\beta}, 0 < x < 1$$
(2)

Figure 1 showed the behavior of pdf and cdf of the Kumaraswamy distribution at different values of the parameters α and β



(a) pdf of the Kumaraswamy distribution(b) cdf of the Kumaraswamy distribution

Figure 1: Behavior of Kumaraswamy distribution

In industrial life testing and medical survival analysis, it is common for the object of interest to be lost or withdrawn before failure, or for the object's lifetime to be only known within an interval. This results in a sample that is incomplete, often referred to as a censored sample. There are various reasons for removal of experimental units, such as saving them for future use, reducing total test time, or lowering associated costs. Right censoring is a technique used in life-testing experiments to handle censored samples. The conventional Type-I and Type-II censoring schemes are the most common methods of right censoring, but they do not allow for removal of units at points other than the terminal point of the experiment, limiting their

flexibility. To address this limitation, a more general censoring scheme called the progressive Type-II censoring scheme has been proposed. as follows:

- Suppose that *n*unite are placed on a test at time zero with *m* failures to be observed.
- At the first failure, say $x_{(1)}$, R_1 of the remaining units are randomly selected and removed.
- At the time of the second failure, $x_{(2)}$, R_2 of the remaining units are selected and removed.
- Finally, at the time of the m^{th} failure the rest of the units are all removed, $R_m = n R_1 R_2 \dots R_{m-1} m$.
- Thus, it is possible to witness the data {(x₍₁₎, R₁), ..., (x_(m), R_m)} during a gradual censorship plan. Even though R₁, R₂, ..., R_m are encompassed as a section of the data, their values are previously known.

The joint probability density function of all *m*progressive Type-II censoring schemestatistics is (Balakrishnan and Aggarwala (2000))

$$L(\alpha,\beta) = C \prod_{i=1}^{m} (f(x_{(i)};\alpha,\beta)) (1 - F(x_{(i)};\alpha,\beta))^{R_i}$$
(3)

where

 $C = n(n - R_1 - 1) \dots (n - R_1 - R_2 - \dots - R_m - m + 1)$

If $R_1 = R_2 = \cdots = R_{m-1} = 0$, then $R_i = n - m$ which corresponds to the Type-II censoring. and If $R_1 = R_2 = \cdots = R_m = 0$, then n = m which corresponds to the complete sample (Wu (2002)).

Sindhu et al. (2013) studied the Bayesian and non-Bayesian estimation for the shape parameter of the Kumaraswamy distribution under Type-II censored samples. They obtained maximum likelihood estimation and Bayes estimation using asymmetric loss functions: Degroot loss function, LINEX loss function and General Entropy loss function. They derived Posterior predictive distributions along with posterior predictive intervals under simple and mixture priors. Reyad and Ahmed (2016) introduced the Bayesian and E-Bayesian estimation for the shape parameter of the Kumaraswamy distribution based on Type-II censored schemes. They derived estimates under symmetric loss function [squared error loss] and three asymmetric loss functions: LINEX loss function, Degroot loss function and Quadratic loss function. Ghosh and Nadarajah (2017) discussed Bayesian estimation of Kumaraswamy distributions based on three different types of censored samples: left censoring, singly Type-II censoring and doubly Type-II censoring. They obtained Bayes estimates using two different types of loss functions: LINEX and Quadratic. Pak and Rastogi (2018) considered non-Bayesian and Bayesian estimation of Kumaraswamy parameters when the data are Type-II hybrid censored. The maximum likelihood estimates and its asymptotic variancecovariance matrix are obtained. They used the asymptotic variances and covariance's of the MLEs to construct approximate confidence intervals. In addition, by using the parametric bootstrap method, discussed the construction of confidence intervals for the unknown parameter. Sultana et al. (2018) considered estimation of unknown parameters of a two-parameter Kumaraswamy distribution with hybrid censored samples. They obtained

maximum likelihood estimates using an EM algorithm. Bayes estimates were derived under the squared error loss function using different approximation methods and an importance sampling technique is also discussed. El-Deen *et* al. (2014) studied non-Bayesian and Bayesian approaches to obtain point and interval estimation of the shape parameters, the reliability and the hazard rate functions of the Kumaraswamy distribution. The estimators are obtained based on generalized order statistics. The symmetric and asymmetric loss functions, the squared error loss function (as a symmetric loss function), LINEX, precautionary and general entropy loss functions (as asymmetric loss functions) are considered for Bayesian estimation. Also, maximum likelihood and Bayesian prediction for a new observation are found. The results have been specialized to Type-II censored data and the upper record values. Kohansal and Bakouch (2019) described the point and interval estimation of the unknown parameters of Kumaraswamy distribution under the adaptive Type-II hybrid progressive censored samples. They obtained the maximum likelihood estimation of the parameters. In addition, the Bayesian estimation of the parameters is approximated by using the MCMC algorithm and Lindley's method due to the lack of explicit forms. Sultana et al. (2020) investigated the estimation problems of unknown parameters of the Kumaraswamy distribution under Type-I progressive hybrid censoring. They derived the maximum likelihood estimates of parameters using an EM algorithm. Bayes estimates were obtained under different loss functions using the Lindley method and importance sampling procedure. Tu and Gui (2020) discussed and considered the estimation of unknown parameters featured by

the Kumaraswamy distribution on the condition of a generalized progressive hybrid censoring scheme. They derived the maximum likelihood estimators and Bayesian estimators under symmetric loss functions and asymmetric loss functions, like general entropy, squared error as well as Linex loss function. Since the Bayesian estimates fail to be of explicit computation, Lindley approximation, as well as the Tierney and Kadane method, is employed to obtain the Bayesian estimates. Ghafouri and Rastogi (2021) considered the estimation of the parameters and reliability characteristics of Kumaraswamy distribution using progressive first failure censored samples. They derived the maximum likelihood estimates using an EM algorithm and compute the observed information of the parameters that can be used for constructing asymptotic confidence intervals. Also, they computed the Bayes estimates of the parameters using Lindley approximation as well as the Metropolis-Hastings algorithm. Gholizadeh et al. (2011) studied the Bayesian and non-Bayesian estimators for the shape parameter, reliability and failure rate functions of the Kumaraswamy distribution in the cases of progressively Type-II censored samples. Maximum likelihood estimation and Bayes estimation, reliability and failure rate functions are obtained using symmetric and asymmetric loss functions, like squared error loss, Precautionary and LINEX loss functions. Feroze and Elbatal (2013) considered the estimation of two parameters of the Kumaraswamy distribution under progressive Type-II censoring with random removals, where the number of units removed at each failure time has a binomial distribution. They obtained the maximum likelihood estimation of the unknown parameters, and the asymptotic

variance-covariance matrix was also obtained. Also, they derived the formula to compute the expected test time. Eldin et al. (2014) studied the Estimation for parameters of the Kumaraswamy distribution based on progressive Type-II censoring. They derived estimates using the maximum likelihood and Bayesian approaches. In the Bayesian approach, the two parameters are assumed to be random variables and estimators for the parameters are obtained using squared error loss function. Erick et al. (2016) considered the parameter estimation problem of test units from Kumaraswamy distribution based on progressive Type-II censoring scheme. The maximum likelihood Estimates of the parameters are derived using EM algorithm. Also the expected Fisher information matrix based on the missing value principle is computed. EL-Sagheer (2019) used the maximum likelihood, Bayes, and parametric bootstrap methods for estimating the unknown parameters, as well as some lifetime parameters reliability and hazard functions, based on progressively Type-II right-censored samples from a two-parameter Kumaraswamy distribution. The classical Bayes estimates proposed by applying the Markov chain Monte Carlo (MCMC) technique.

2. Maximum Product Spacings

Ng *et al.* (2012) and El-Sherpieny*et al.* (2020) introduced maximum product spacing (MPS) method based on progressive Type-II censoring scheme sample method, MPS method chooses the parameter values that make the observed data as uniform as possible, according to a specific quantitative measure of uniformity.

$$G(\alpha,\beta) = \prod_{i=1}^{m+1} \left(F(x_{(i)};\alpha,\beta) - F(x_{(i-1)};\alpha,\beta) \right) \prod_{i=1}^{m} \left(1 - F(x_{(i)};\alpha,\beta) \right)^{R_i}$$

from (2), one can get:

$$G(\alpha,\beta) = \prod_{i=1}^{m+1} \left\{ \left(1 - x_{(i-1)}^{\alpha}\right)^{\beta} - \left(1 - x_{(i)}^{\alpha}\right)^{\beta} \right\} \prod_{i=1}^{m} \left(1 - x_{(i)}^{\alpha}\right)^{\beta R_{i}}$$

The natural logarithm of the product spacings function is

$$S(\alpha,\beta) = \sum_{i=1}^{m+1} \log\left\{ \left(1 - x_{(i-1)}^{\alpha}\right)^{\beta} - \left(1 - x_{(i)}^{\alpha}\right)^{\beta} \right\} + \sum_{i=1}^{m} \beta R_{i} \log(1 - x_{(i)}^{\alpha})$$

where $S(\alpha, \beta) = \log C(\alpha, \beta)$

where $S(\alpha, \beta) = \log G(\alpha, \beta)$.

The MPS estimators of α and β , denoted by $\hat{\alpha}_{MPS}$ and $\hat{\beta}_{MPS}$, respectively, are obtained by solving the following normal equations simultaneously

$$\begin{aligned} \frac{\partial S(\alpha,\beta)}{\partial \alpha} &= \sum_{i=1}^{m} \beta R_{i} \frac{-x_{(i)}^{\alpha} \log(x_{(i)})}{(1-x_{(i)}^{\alpha})} \\ &+ \sum_{i=1}^{m+1} \left[\frac{\beta (1-x_{(i)}^{\alpha})^{\beta-1} x_{(i)}^{\alpha} \log(x_{(i)}) - \beta (1-x_{(i-1)}^{\alpha})^{\beta-1} x_{(i-1)}^{\alpha} \log(x_{(i-1)})}{(1-x_{(i-1)}^{\alpha})^{\beta} - (1-x_{(i)}^{\alpha})^{\beta}} \right] \\ &= 0, \end{aligned}$$

and

$$\frac{\partial S(\alpha,\beta)}{\partial \beta} = \sum_{i=1}^{m} R_i \log(1 - x_{(i)}^{\alpha})$$
$$+ \sum_{i=1}^{m+1} \left[\frac{\left(1 - x_{(i-1)}^{\alpha}\right)^{\beta} \log(1 - x_{(i-1)}^{\alpha}) - \left(1 - x_{(i)}^{\alpha}\right)^{\beta} \log(1 - x_{(i)}^{\alpha})}{\left(1 - x_{(i-1)}^{\alpha}\right)^{\beta} - \left(1 - x_{(i)}^{\alpha}\right)^{\beta}} \right]$$
$$= 0$$

The MPS, $\hat{\alpha}_{MPS}$ and $\hat{\beta}_{MPS}$ are the solution of the two nonlinear equations that the system needs to be solved numerically to obtain parameters estimation values.

3.Simulation Study

In this simulation, the average and mean square error using the MPC Method for Parameters estimation of Kumaraswamy distribution based on a progressive Type-II censoring scheme are now computed using a number of replications 1000using R-Statistical Programming Language for Statistical Computing, based on the following assumptions:

- 1. values of $(\alpha, \beta) = (0.5, 0.5), (0.5, 1), (1, 2), \text{ and } (1, 1).$
- 2. Sample sizes of n = 40, n = 80 and n = 100.
- 3. In this simulation, the algorithm proposed by Balakrishnan and Sandhu (1995)can be used to generate a progressively Type-II censored sample, removed items R_i are assumed at different sample sizes n and the number of stages m as shown in Table (1).

n	m	censoring schemes					
		<i>S</i> ₁	<i>S</i> ₂	S ₃	<i>S</i> ₄		
40	20	(20, 0 ^{*19})	$(10, 0^{*18}, 10)$	(0 ^{*9} , 10, 10, 0 ^{*9})	(0*19, 20)		
40	30	(10, 0*29)	$(5,0^{*28},5)$	$(0^{*14}, 5, 5, 0^{*14})$	(0 ^{*29} , 10)		
80	40	(40, 0 ^{*39})	(20, 0*38, 20)	$(0^{*19}, 20, 20, 0^{*19})$	(0 ^{*39} , 40)		
80	60	(20, 0 ^{*59})	$(10, 0^{*58}, 10)$	$(0^{*29}, 10, 10, 0^{*29})$	(0*59, 20)		
100	60	(40, 0 ^{*59})	(20, 0*58, 20)	$(0^{*29}, 20, 20, 0^{*29})$	(0*59, 40)		
100	80	(20, 0 ^{*79})	$(10, 0^{*78}, 10)$	(0*39, 10, 10, 0*39)	(0*79, 20)		

 Table (1): Numerous patterns for removing items from life test at different number of stages

Here, $(2^{*3}, 0)$, for example, means that the censoring scheme employed is (2,2,2,0).

Based on the generated data, we compute the MPSs. In tables (2,3), we display the estimates obtained by using MPS at different values of n and m, respectively. Further, the first column represents the average estimates (Avg.) and the second column represents the mean square error (MSE).

From Tables (2,3), we observed that the Avg. and MSE of the estimates are close together. As a general result, we see that when n increases, for all cases, the MSE decrease.

Table (2): Average, MSE for MPS of the Kumaraswamy distribution for different progressive Type-II censoring scheme at different values of α , β ,n, and m.

(n . m)	Sch.	Parm.	$\alpha = 0.05, \beta$ $= 0.05$		$\alpha = 0.05, \beta = 1$	
	~		Avg.	MSE	Avg.	MSE
	C	α	0.6925	0.0919	0.6467	0.0524
	\mathcal{S}_1	β	0.6665	0.0812	1.4239	0.5218
	c	α	0.6379	0.0621	0.6057	0.0390
(40, 20)	3 ₂	β	0.6164	0.0746	1.3238	0.5548
(40, 20)	<i>S</i> ₃	α	0.6697	0.0693	0.6355	0.0438
		β	0.7133	0.1368	1.5564	0.9635
	<i>S</i> ₄	α	0.6335	0.0602	0.6063	0.0405
		β	0.6382	0.1082	1.4027	0.9064
	c	α	0.6593	0.0645	0.6202	0.0367
	S_1	β	0.6137	0.0388	1.2881	0.2362
	<i>S</i> ₂	α	0.6270	0.0507	0.5929	0.0292
(40, 30)		β	0.5780	0.0299	1.2043	0.1872
(10,00)	C	α	0.6511	0.0584	0.6162	0.0344
	53	β	0.6259	0.0468	1.3223	0.2971
	<i>S</i> ₄	α	0.6209	0.0483	0.5900	0.0289

		-	0.5500	0.0005	1 2 1 1 1	0.01.7.4
		β	0.5780	0.0325	1.2111	0.2156
	<i>S</i> ₁	α	0.6050	0.0299	0.5819	0.0184
		β	0.5803	0.0213	1.1992	0.1207
	6	α	0.5749	0.0214	0.5581	0.0143
(80, 40)	\mathcal{S}_2	β	0.5539	0.0194	1.1452	0.1210
(80, 40)	c	α	0.5899	0.0224	0.5726	0.0148
	\mathcal{S}_3	β	0.5987	0.0306	1.2460	0.1820
	c	α	0.5713	0.0206	0.5573	0.0145
	\mathcal{S}_4	β	0.5625	0.0299 0.0213 0.0214 0.0194 0.0224 0.0306 0.0206 0.0252 0.0219 0.0123 0.0177 0.0104 0.0189 0.0142 0.0167 0.0123 0.0155 0.0154 0.0155 0.0155 0.0155 0.0155 0.0155 0.0155 0.0155 0.0155 0.0155 0.0155 0.0155 0.0155 0.0152 0.0080 0.0127 0.0068 0.0136 0.0072	1.1732	0.1701
	c	α	0.5835	0.0219	0.5634	0.0130
	S_1	β	0.5573	0.0123	1.1412	0.0687
	c	α	0.5654	0.0177	0.5477	0.0107
(80, 60)	3 ₂	β	0.5380	0.0104	1.0968	0.0590
(80, 00)	c	α	0.5773	0.0189	0.5600	0.0116
	\mathcal{S}_3	β	0.5624	0.0142	1.1545	0.0807
	c	α	0.5616	0.0167	0.5459	0.0105
	\mathcal{S}_4	β	0.5379	0.0112	1.0993	0.0662
	<i>S</i> ₁	α	0.5805	0.0203	0.5618	0.0123
		β	0.5569	0.0122	1.1402	0.0676
	c	α	0.5594	0.0154	0.5446	0.0099
(100, 60)	3 ₂	β	0.5375	0.0110	1.0982	0.0648
(100, 00)	S	α	0.5700	0.0155	0.5554	0.0099
	53	β	0.5657	0.0155	1.1620	0.0879
	S	α	0.5557	0.0144	0.5433	0.0098
	54	β	0.5407	0.0130	1.1097	0.0811
	S	α	0.5642	0.0152	0.5488	0.0092
	51	β	0.5438	0.0080	1.1075	0.0447
	S	α	0.5508	0.0127	0.5368	0.0078
(100.80)	52	β	0.5291	0.0068	1.0730	0.0386
(100, 00)	<i>S</i> ₃	α	0.5601	0.0136	0.5466	0.0084
		β	0.5467	0.0090	1.1152	0.0507
	S.	α	0.5479	0.0121	0.5352	0.0076
	\mathcal{I}_4	β	0.5282	0.0072	1.0727	0.0420

Notes: Sch. – scheme, Parm. – Parameter.

(22, 222)	Sah	Domm	$\alpha = 1, \beta = 2$		$\alpha = 1, \beta = 1$	
$(\boldsymbol{n},\boldsymbol{m})$	Sch.	rarm.	Avg.	MSE	Avg.	MSE
	C	α	1.2454	0.1456	1.2935	0.2098
	$\begin{array}{c c c c c c c c c c c c c c c c c c c $	0.5218				
	C	α	1.1776	0.1162	1.2114	0.1559
(40, 20)	S_2	β	2.9212	4.6127	1.3238	0.5547
(40, 20)	C	α	1.2339	0.1298	1.2710	0.1753
	\mathcal{S}_3	β	3.4893	7.5024	1.5564	0.9634
	C	α	1.1838	0.1269	1.2126	0.1621
	\mathcal{S}_4	β	3.1945	8.5153	1.4027	0.9066
	C	α	1.1989	0.1006	1.2405	0.1471
	S_1	β	2.7501	1.5818	1.2881	0.2362
	C	α	1.1500	0.0812	1.1858	0.1169
(40, 20)	S_2	β	2.5467	1.2949	1.2043	0.1871
(40, 50)	<i>S</i> ₃	α	1.1948	0.0966	1.2324	0.1378
(,)		β	2.8430	2.0558	1.3223	0.2971
	C	α	1.1477	0.0830	1.1801	0.1157
	\mathcal{S}_4	β	2.5802	1.5758	1.2111	0.2156
	c	α	1.1382	0.0528	1.1638	0.0737
	\mathcal{S}_1	β	2.5070	0.7435	1.1992	0.1207
	C	α	1.0980	0.0438	1.1163	0.0573
(80, 40)	3 ₂	β	2.3929	0.8114	1.1451	0.1210
(80, 40)	c	α	1.1258	0.0445	1.1453	0.0593
	3 3	β	2.6213	1.1478	1.2460	0.1819
	C	α	1.0995	0.0466	1.1148	0.0583
	\mathcal{S}_4	β	2.4799	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	0.1702	
	c	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	0.0363	1.1269	0.0521	
(80, 60)	$ _{\mathcal{S}_1}$	β	2.3560	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$		
(00,00)	c	α	1.0768	0.0307	1.0956	0.0430
	3 ₂	β	2.2506	0.3588	1.0969	0.0590

Table (3): Average, MSE for MPS of the Kum. distribution for different progressive Type-II censoring schemeat different values of α , β , n, and m.

	S ₃	α	1.1012	0.0332	1.1200	0.0465
		β	2.3888	0.4833	1.1545	0.0807
	C	α	1.0751	0.0311	1.0918	0.0422
	\mathcal{S}_4	β	2.2625	0.4168	1.0992	0.0662
	C	α	1.1032	0.0346	1.1237	0.0492
	\mathcal{S}_1	β	2.3530	0.4012	1.1402	0.0676
	C	α	1.0735	0.0294	1.0893	0.0396
(100, 60)	S_2	β	2.2593	0.4049	1.0982	0.0647
(100, 00)	<i>S</i> ₃	α	1.0949	0.0291	1.1109	0.0397
		β	2.4049	0.5212	1.1621	0.0879
	<i>S</i> ₄	α	1.0731	0.0303	1.0866	0.0392
		β	2.2955	0.5299	1.1097	0.0812
	c	α	1.0811	0.0257	1.0977	0.0368
	\mathcal{S}_1	β	2.2697	0.2654	1.1075	0.0446
	<i>S</i> ₂	α	1.0588	0.0222	1.0737	0.0312
(100, 80)		β	2.1867	0.2324	1.0730	0.0386
(100, 80)	<i>S</i> ₃	α	1.0782	0.0239	1.0930	0.0336
		β	2.2883	0.3026	1.1150	0.0508
	c	α	1.0569	0.0223	1.0704	0.0306
	\mathcal{S}_4	β	2.1896	0.2599	1.0728	0.0421

Notes: Sch. - scheme, Parm. - Parameter.

4.Real Data

In this section, we analyze a real data set which describes the monthly water capacity from the Shasta reservoir in California, USA. The data are recorded for the month of February from 1991 to 2010 see Sultana *et al.* (2018) and Sultana *et al.* (2020). The data points are listed below as follows. 0.338936, 0.431915, 0.759932, 0.724626, 0.757583, 0.811556, 0.785339, 0.783660, 0.815627, 0.847413, 0.768007, 0.843485, 0.787408, 0.849868, 0.695970, 0.842316, 0.828689, 0.580194, 0.430681, 0.742563.

To determine if the considered dataset can be appropriately analyzed using a Kum. distribution, a goodness of fit test is conducted. In addition to Kum. distribution, we also fit generalized exponential [Gen.Exp], Burr XII [Burr], and beta distributions to the data set. We judge the goodness of fit using various criteria, for example, negative log-likelihood criterion (NLC), Akaike information criterion (AIC) introduced by Akaike (1969), corrected AIC (AICc) introduced by Hurvich and Tsai (1989), and Bayesian information criterion (BIC) introduced by Schwarz (1978). The smaller the value of these criteria, the better the model fits the data. The results are shown in Table (4). Besides, the histogram and empirical cumulative distribution functions are given respectively in Figure 3.

 Table (4). Goodness of fit tests for different distributions for real data

Distribution	NLS	AIC	AICc	BIC	K-S	p-Value
Kum.	-13.4747	-22.9494	-22.2435	-20.9579	0.2208	0.2446
Gen.Exp	-4.7925	-5.5851	-4.8791	-3.5936	0.2948	0.0490
Burr	-11.5059	-19.0118	-18.3059	-17.0204	0.2247	0.2276
beta	-12.5619	-21.1238	-20.4179	-19.1323	0.2359	0.1833



Figure 2: Goodness of fit tests for real data

Referring to the values reported in table (4), we conclude that the Kumaraswamy distribution fits the data set good compared to the other models. Thus, the various point and interval estimates of α and β for real data under progressive censoring schemes as following as in table(5).

In table (5), we display the estimates obtained by using MPS at m = 10. we computed the average estimates (Avg.) and standard deviation (SD). From Tables (5), we observed that the Avg. and MSE of the estimates are close together.

n m		Sch	Sch Parm		MPS		
11	111	Scn.	1 al III.	Avg.	SD		
		C	α	12.9105	4.3516		
2		\mathcal{S}_1	β	23.4821	24.7160		
	1 0	c	α	8.6988	3.2672		
		S_2	β	3.7516	2.9224		
0		c	α	17.2251	5.2833		
		S_3	β	36.6941	47.8674		
		c	α	7.8385	3.0958		
		\mathcal{S}_4	β	2.0032	1.4750		

Table (5).Point and interval estimates of α and β for MPS of the Kumaraswamy distribution under progressive censoring schemes.

5. Conclusion

In this paper, we have considered the problem of estimation of the unknown parameters for Kumaraswamy distribution under progressive Type-II censoring. We derived maximum product spacings estimates for the unknown parameters of a Kumaraswamy distribution. In this paper, although we have mainly considered Type-II progressive censoring cases, the same method can be extended to other censoring schemes also.

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الملخص:

في هذا البحث درسنا مشكلة تقدير النقاط لمعلمات توزيع كومار اسوامي على أساس الرقابة التدريجية من النوع الثاني. يتم استخدام الحد الأقصى لتباعد المنتج لتقدير معلمات النموذج. لتقييم أداء مقدر النقاط ، يتم إجراء در اسة المحاكاة. لتوضيح فائدة الدر اسة في الممارسة العملية ، تم أيضًا أخذ مجموعة بيانات حقيقية في الاعتبار.

الكلمات المفتاحية:

توزيع كومار اسوامي ، الرقابة التدريجية من النوع الثاني ، تقدير المسافات القصوى للمنتج